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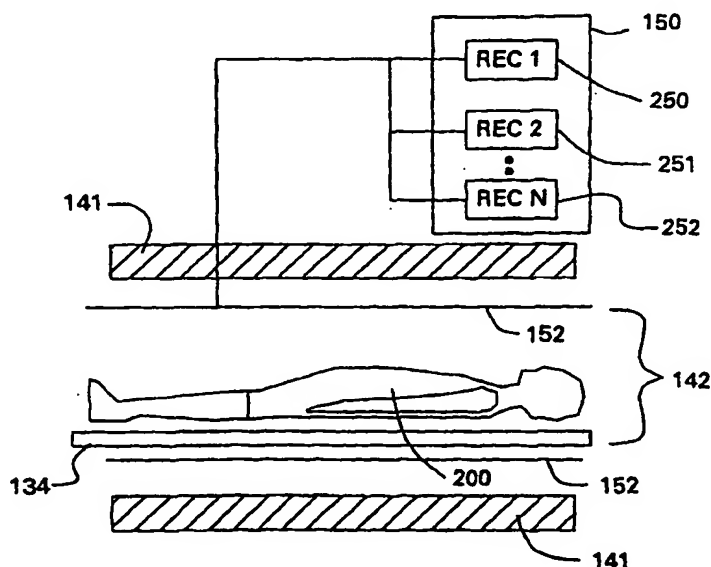
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(54) **Extended volume imaging using MRI with parallel reception**

(57) A method and apparatus for producing an image from an extended volume of interest within a subject (200) using a Magnetic Resonance Imaging (MRI) system are provided. The method comprises translating the volume using a positioning device (134) along an axis of the MRI system. A plurality of MR signals are detected from at least one radiofrequency (RF) coil array (152) for a given field-of-view within the MRI system as the

positioning device is translated. The plurality of MR signals are sent to a plurality of receivers (250-252) wherein the receivers are each adapted to adjust their respective center frequencies at a rate commensurate with a rate of translation of the positioning device. A plurality of respective sub-images corresponding to the plurality of MR signals for each of the plurality of receivers are combined to form a composite image of the volume of interest.



**FIG. 2**

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## Description

**[0001]** This invention relates to a method and system for medical imaging. More particularly, this invention relates to a method and system for extended volume imaging using a Magnetic Resonance Imaging (MRI) system and employing a moving patient table.

**[0002]** Certain clinical situations require that a head-to-toe scan of a patient be made. For example, metastatic cancer can occur anywhere in the body and patients at risk for metastatic disease need to be evaluated regularly. Currently head-to-toe or, alternatively, extended volume imaging is generally performed with whole body positron emission tomography (PET) systems or nuclear studies in which small amounts of radioactive substances are given to the patient and allowed to collect in regions of rapid tumor growth. The imaging sensitivity and specificity of magnetic resonance (MR), however, makes MR a more desirable choice for diagnosis particularly when Gadolinium (Gd) contrast agents are employed. Gd contrast agents are typically administered intravenously and tend to collect in regions of angiogenesis associated with active tumors. Unfortunately, MR scanners have limited sensitive volumes and whole body scanning requires that a series of images be made at different stations. Patient motion and table registration can make the joining of these separate images a challenge and tend to create image artifacts referred to as "stitching artifacts".

**[0003]** Generally, imaging using a MRI system involves imaging a volume of interest in a MRI scanner's usable volume. The usable volume is defined as a contiguous area inside the patient bore of a Magnetic Resonance scanner and it can be limited in size. Typically, when the usable volume fails to cover an extended object, a method for examining the whole volume containing the object employs repeated executions of positioning and imaging a fraction of the whole volume within the scanner's usable volume to obtain regional images. A subsequent assembling operation then assembles or "stitches" the regional images together to produce a final image of the whole volume of interest. Such an approach is typically challenged by the "stitching" artifact issue wherein resulting final images often suffer from distinctive artifacts at the boundaries of the "stitched" pieces.

**[0004]** Existing techniques achieve correct combination of regional images through full spatial encoding along patient table motion direction. With other existing methods, the patient table is held stationary while data is collected and moved between the collection of the regional images. These techniques minimize "stitching" artifacts by using slab selection profiles that are as rectangular as possible, and/or discarding image data near the boundaries. As a result, these techniques tend to be inflexible, require prolonged radio frequency (RF) excitation, and involve considerable acquisition efficiency degradation.

**[0005]** More recently, imaging an extended volume is performed by means of simultaneous patient table translation thereby allowing examination of a field of view that extends beyond the usable volume of an MR scanner. It is however very difficult to achieve 3-dimensional whole body coverage with favorable mapping accuracy, spatial resolution, signal-to-noise ratio and total scan time.

**[0006]** Parallel imaging offers a way to speed up conventional MR imaging. The idea of detecting MR signal with multiple coils receiving in parallel has been explored. Recent advances represented by simultaneous acquisition of spatial harmonics (referred to as SMASH) and sensitivity encoding (SENSE) make up for a reduced number of gradient-driven spatial encodes by integrating data from an array of receive RF coils. SMASH and the likes assume a frequency perspective - they fill up skipped k-space lines through approximating Fourier harmonics with linearly combined coil sensitivity profiles. SENSE and related methods adopt a space perspective - they resolve localization ambiguities through algebraically extracting additional spatial information encoded with the sensitivity profiles.

**[0007]** What is needed is a method and system for extended volume imaging, such as head-to-toe imaging, using a MRI system to reduce the imaging time while offering good image quality.

**[0008]** In a first aspect of the present invention, an imaging apparatus for producing Magnetic Resonance (MR) images of a subject is provided. The apparatus comprises a magnet assembly for producing a static magnetic field, a gradient coil assembly for generating a magnetic field gradient for use in producing MR images, at least one radiofrequency (rf) coil array disposed about the subject for transmitting a radiofrequency pulse and for detecting a plurality of magnetic resonance (MR) signals induced from the subject, a positioning device for supporting the subject and for translating the subject into the magnet assembly, and, a plurality of receivers for receiving the plurality of MR signals, the receivers each being adapted to adjust their respective center frequencies at a rate commensurate with a rate of translation of the positioning device.

**[0009]** In a second aspect of the invention, a method for producing an image from an extended volume of interest within a subject using a Magnetic Resonance Imaging (MRI) system where the extended volume of interest is larger than an imaging portion of a magnet within the MRI system is provided. The method comprises translating the volume using a positioning device along an axis of the MRI system. A plurality of MR signals are detected from at least one radiofrequency (RF) coil array for a given field-of-view within the MRI system as the positioning device is translated. The plurality of MR signals are sent to a plurality of receivers wherein the receivers are each adapted to adjust their respective center frequencies at a rate commensurate with a rate of translation of the positioning device. A plurality of re-

spective sub-images corresponding to the plurality MR signals for each of the plurality of receivers are combined to form a composite image of the volume of interest.

**[0010]** The features and advantages of the present invention will become apparent from the following detailed description of the invention when read with the accompanying drawings in which:

Figure 1 illustrates a simplified block diagram of a Magnetic Resonance Imaging system to which embodiments of the present invention are useful;

Figure 2 is a side-view block diagram of a receiver arrangement for use in the MRI system of Figure 1 and to which embodiments of the present invention are applicable;

Figure 3 is a simplified graphical illustration of a data acquisition sequence to which embodiments of the present invention are applicable; and,

Figure 4 is a simplified graphical illustration of a trans-axial view of a RF coil array for use in the MRI system of Figure 1 and to which embodiments of the present invention are applicable.

**[0011]** FIG. 1 illustrates a simplified block diagram of a system for producing images in accordance with embodiments of the present invention. In an embodiment, the system is a MR imaging system which incorporates the present invention. The MR system could be, for example, a GE-Signa MR scanner available from GE Medical Systems, Inc., which is adapted to perform the method of the present invention, although other systems could be used as well.

**[0012]** The operation of the MR system is controlled from an operator console 100 that includes a keyboard and control panel 102 and a display 104. The console 100 communicates through a link 116 with a separate computer system 107 that enables an operator to control the production and display of images on the screen 104. The computer system 107 includes a number of modules that communicate with each other through a backplane. These include an image processor module 106, a CPU module 108, and a memory module 113, known in the art as a frame buffer for storing image data arrays. The computer system 107 is linked to a disk storage 111 and a tape drive 112 for storage of image data and programs, and it communicates with a separate system control 122 through a high speed serial link 115.

**[0013]** The system control 122 includes a set of modules connected together by a backplane. These include a CPU module 119 and a pulse generator module 121 that connects to the operator console 100 through a serial link 125. It is through this link 125 that the system control 122 receives commands from the operator that indicate the scan sequence that is to be performed. The

pulse generator module 121 operates the system components to carry out the desired scan sequence. It produces data that indicate the timing, strength, and shape of the radio frequency (RF) pulses which are to be produced, and the timing of and length of the data acquisition window. The pulse generator module 121 connects to a set of gradient amplifiers 127, to indicate the timing and shape of the gradient pulses to be produced during the scan. The pulse generator module 121 also receives subject data from a physiological acquisition controller 129 that receives signals from a number of different sensors connected to a subject 200, such as ECG signals from electrodes or respiratory signals from a bellows. And finally, the pulse generator module 121 connects to a scan room interface circuit 133 which receives signals from various sensors associated with the condition of the subject 200 and the magnet system. It is also through the scan room interface circuit 133 that a positioning device 134 receives commands to move the subject 200 to the desired position for the scan.

**[0014]** The gradient wave forms produced by the pulse generator module 121 are applied to a gradient amplifier system 127 comprised of  $G_x$ ,  $G_y$  and  $G_z$  amplifiers. Each gradient amplifier excites a corresponding gradient coil in an assembly generally designated 139 to produce the magnetic field gradients used for position encoding acquired signals. The gradient coil assembly 139 forms part of a magnet assembly 141 which includes a polarizing magnet 140 and a RF coil 152. Volume 142 is shown as the area within magnet assembly 141 for receiving subject 200 and includes a patient bore. As used herein, the usable volume of a MRI scanner is defined generally as the volume within volume 142 that is a contiguous area inside the patient bore where homogeneity of main, gradient and RF fields are within known, acceptable ranges for imaging. A transceiver module 150 in the system control 122 produces pulses that are amplified by an RF amplifier 151 and coupled to the RF coil 152 by a transmit/receive switch 154. In an embodiment of the present invention, transceiver module 150 comprises a plurality of receivers that will be discussed in greater detail with reference to Figure 2. The resulting signals radiated by the excited nuclei in the subject 200 may be sensed by the same RF coil 152 and coupled through the transmit/receive switch 154 to a preamplifier 153. The amplified MR signals are demodulated, filtered, and digitized in the receiver section of the transceiver 150. The transmit/receive switch 154 is controlled by a signal from the pulse generator module 121 to electrically connect the RF amplifier 151 to the coil 152 during the transmit mode and to connect the preamplifier 153 during the receive mode. The transmit/receive switch 154 also enables a separate RF coil (for example, a head coil or surface coil) to be used in either a transmit or receive mode. It is to be appreciated that RF coil 152 is configured to be operable for MRI scanning as described below, in which a subject is translated on a positioning device along the z-axis. As used herein,

"adapted to", "configured" and the like refer to mechanical or structural connections between elements to allow the elements to cooperate to provide a described effect; these terms also refer to operation capabilities of electrical elements such as analog or digital computers or application specific devices (such as an application specific integrated circuit (ASIC)) that is programmed to perform a sequel to provide an output in response to given input signals.

**[0015]** As is well-known, RF coil 152 is used for detecting MR signals from the region of interest that is to be imaged, e.g. whole-body coil, surface coil or head coil. To image an extended volume, a whole-body coil is desirably used for RF coil 152. A whole-body coil may be a conventional and well-known birdcage coil configuration or, alternatively a variety of coil structures comprises a plurality of conductors formed in a substantially circular form interconnected structurally and electrically that is disposed about a subject to be imaged. The conductors are desirably of sufficient length to detect signals in a desired field-of-view as is also well-known. For embodiments of the present invention, RF coil 152 is a receive coil array comprising a plurality of elements arranged in an array and will be described in greater detail with reference to Figure 4.

**[0016]** The MR signals picked up by RF coil 152 are digitized by the transceiver module 150 and transferred to a memory module 160 in the system control 122. When the scan is completed and an entire array of data has been acquired in the memory module 160, an array processor 161 operates to Fourier transform the data into an array of image data. These image data are conveyed through the serial link 115 to the computer system 107 where they are stored in the disk memory 111. In response to commands received from the operator console 100, these image data may be archived on the tape drive 112, or they may be further processed by the image processor 106 and conveyed to the operator console 100 and presented on the display 104. As will be discussed with reference to embodiments below, further processing is performed by the image processor 106 that includes reconstructing acquired MR image data according to embodiments described below.

**[0017]** Referring to Figure 2, there is shown a side-view block diagram of a receiver arrangement for use in the MRI system of Figure 1. As shown in Figure 2, subject 200 is positioned on positioning device 134 of the MR scanner. As used herein, MR scanner refers generally to the MRI system. Subject 200 is translated through the useable volume (142 of Figure 1) of the scanner at a constant rate until the entire body of the subject (or desired portion thereof) has passed through magnet assembly 141 (Figure 1).

**[0018]** Thus, an imaging apparatus for producing Magnetic Resonance (MR) images of a subject is provided. The apparatus comprises a magnet assembly for producing a static magnetic field; a gradient coil assembly for generating a magnetic field gradient for use in

producing MR images; at least one radiofrequency (rf) coil assembly for transmitting a radiofrequency pulse and for detecting a plurality of MR signals induced from the subject; a positioning device for supporting the subject and for translating the subject into the magnet assembly; and, a plurality of receivers for receiving the plurality of MR signals and being further adapted to be adjusted in phase or frequency changes in response to translation of the positioning device.

**[0019]** Multiple MR sub-images of portions of the subject are made while the subject is moved through the imaging portion of the MR imaging magnet. MR signals are detected from RF coil 152 and simultaneously sent to a plurality, N, of receivers which are shown as 250, 251 and 252 in Figure 2. The description which follows corresponds to an exemplary embodiment in which N=2, and the receivers are receiver 250 and receiver 251. It is to be appreciated that further embodiments would comprise multiple receivers and image processing computations described below would be adapted by one skilled in the art for the selected number N of receivers. At the completion of subject's 200 movement through magnet assembly 141 (Figure 1) the sub-images are processed by image processor 106 (Figure 1) and combined to form a composite image of the entire subject.

**[0020]** The receivers are desirably configured to be adjusted in phase or frequency in response to phase or frequency changes due to translation of the positioning device. During scanning either the phase or the frequency of the receivers (or transmitter) is continuously changed to match the phase and frequency changes of spin magnetization caused by patient motion through the geometrically-fixed gradient system of the magnet.

**[0021]** If it is desirable for the frequency-encoding direction to be parallel to the axis of subject motion, then it is the receiver frequency that is changed at a rate commensurate with the rate of translation of the positioning device (hereinafter "table motion"). The rate of frequency change can be determined from the table motion rate (in cm/sec), the gyromagnetic ratio of the nuclear spins (approx. 4250 Hz/Gauss for 1 H) and the scan rate (TR) (in ms). The table speed can be assumed to be slow during the short periods during data acquisition itself (typically 4-8 ms). In further embodiments, however, the receiver frequency is varied during data acquisition. If the frequency direction is chosen to be parallel to the table motion, then the optimal field-of-view (FOV) for the frequency-encoding direction will be the size of the RF coil divided by N.

**[0022]** If the operator desires that the phase-encoding direction of the image acquisition be parallel to the direction of table motion, then the receiver phase is changed as a function of an incremented position of the positioning device (hereinafter "table position"). In this case the optimal FOV of the phase-encoding direction of each sub-image would be twice the size of the RF coil to prevent phase-wrap artifacts

[0023] If it is desirable for the slice-selection direction of the image to be parallel to the table motion (as in an axial slice), then the transmitter frequency is changed to cause the excitation slice to move through the magnet at the same rate that the subject moves. In this case there are no practical restrictions on the FOV of the sub-image.

[0024] It should also be noted that oblique scanning is possible by performing simple matrix rotations to the gradient subsystem and to the receiver and transmitters frequencies in a manner well known to those skilled in the art.

[0025] Additionally, an additional phase or frequency offset is desirably added to each receiver causing the reconstructed data to be shifted by a distance corresponding to the field-of-view divided by N. In an exemplary embodiment of the invention in which the frequency-encoding axis of each sub-image is parallel to the table motion, the acquisition of a single sub-image is complete in 1/Nth the time it takes the subject to traverse the sensitive imaging volume of the magnet. Furthermore, the order of data acquisition can be modified so that k-space is traversed twice during the acquisition of each sub-image (e.g. odd numbered rows in the first half of the sub-image scan, even numbered rows in the second half). This aspect will be described in greater detail below and with reference to Figure 3.

[0026] Once a sub-image is collected the phase or frequency of the receiver is reset, and a subsequent sub-image at an adjacent location within the subject is acquired. The process is repeated until the subject's entire body has passed through the magnet and has been imaged.

[0027] Because each receiver operates at a different phase or frequency, images acquired with each receiver will contain signals from different portions of the body. The fields-of-view of each receiver overlap each other, however because the relative offsets are FOV/N. Consequently, every part of the subject's body is acquired in a central portion of one sub-image.

[0028] In the exemplary embodiment of the invention, N=2 and 256 lines of k-space are acquired with the frequency direction of the acquisition applied in the direction of table motion. The frequency of both receivers is changed at a rate that causes image acquisition to be performed at the same anatomical location during the acquisition of a sub-image. Furthermore, the sub-images acquired with the two receivers are offset from one another by 1/2 the field-of-view.

[0029] With this embodiment the sequence of data acquisition is as follows:

Receiver 1		Receiver 2	
Sub image #	k-space	Sub image #	k-space
1	odd	--	--
1	even	1.5	even

(continued)

Receiver 1		Receiver 2	
Sub image #	k-space	Sub image #	k-space
2	odd	1.5	odd
2	even	2.5	even
3	odd	2.5	odd
3	even	3.5	even

..... and so on until the entire subject has been imaged.

[0030] In this illustrative example which is shown in Figure 3, the sub-image number represents both the time sequence and the relative location of the sub-image in the context of the subject's anatomy.

[0031] Note that the same RF pulses and magnetic field gradient pulses are used to simultaneously generate data from the subject for both receivers. Because there are N=2 passes through k-space, the pulses used to acquire the second half of sub-image 1 are also used to acquire the first half of sub-image 1.5.

[0032] Once all the data has been acquired, an MR image of the entire body is created by combining the central portions of each sub-image. Since each receiver operates at a unique offset, every portion of the subject is imaged in a central portion of a sub-image and discontinuity artifacts associated with image edge boundaries ("stitching artifacts") are minimized.

[0033] Alternatively, the final composite image is created by combining full sub-images to obtain a composite image with an enhanced signal-to-noise ratio. In this embodiment, each point in the subject's anatomy is found in N sub images. Since these N images have only partially correlated noise, combining the full images will provide a signal-to-noise enhancement. For N=2, the noise in each sub-image is 1/2 correlated since 1/2 of the data in each sub-image is identical. Thus, the expected SNR gain would be  $\sqrt{3/2}$  since the data acquired is equivalent to a 1.5 NEX acquisition. Conversely, if N=3, then the expected SNR gain would be  $\sqrt{5/3}$  or equivalent to a NEX=5/3 acquisition. In general the SNR gain for using N receivers is given by the expression:  $\sqrt{2N-1}$ .

[0034] As N becomes large, the SNR gain approaches  $\sqrt{2}$  or that of a NEX=2 acquisition (i.e. the SNR gain of imaging twice as long).

[0035] A further alternative embodiment employs a single receiver that is operated with the frequency direction applied parallel to the table motion. In this case, the field-of-view of the receiver is set to be equal to a selected active imaging volume less than or equal to the imaging volume. At the beginning of the scan the center of the sub-image is set to be 1/4<sup>th</sup> of the way into the active volume of the imaging system. Sub-images are collected over a period of time that corresponds to the time it takes a selected portion of anatomy to traverse 1/2 of the active imaging volume. Thus at the end of the

acquisition of a sub-image, the center of the sub-image is  $3/4^{\text{th}}$  of the way into the active volume of the imaging system. Upon the completion of the sub-image the next sub-image is initiated with an offset equal to  $1/2$  the FOV. Once all the sub-images have been collected the central portion of each sub-image is extracted and combined with other central portions to form the composite image. As with the prior embodiment, extraction of the central portions of the image reduces the severity of "stitching" artifacts.

**[0036]** In another further embodiment, a single receiver is employed wherein the receiver is adapted to receive the plurality of MR signals from rf coil 152 and is further adapted to be adjusted in at least one of phase and frequency in response to translation the positioning device through the magnet assembly. In this embodiment, the receiver is also further adapted to collect image data for a field-of-view corresponding to a useable volume of the magnet assembly. Thereafter, processing of the MR signals is performed to compute a plurality of respective sub-images for the field-of-view (FOV) at each of a plurality of incremented positions as the subject is translated. A central portion of each of the plurality of respective sub-images is combined to form a composite image of the volume of interest.

**[0037]** Referring to Figure 4, an embodiment for the present invention employs a separate RF receive coil array 353 that complements RF coil 152 (of Figure 1). During moving table imaging, RF coil 152 is used for transmission and coil array 353 is used for reception. Arranging coil array elements 300 of coil array 353 (combination of elements 300 comprises the receive coil array) such that they distribute in dimensions orthogonal relative to the frequency encoding direction is desirable for reducing phase encoding steps and speeding up the imaging. For moving table imaging methods that frequency-encode along the table translation direction, a preferred embodiment employs coil array 353 of coil array elements 300 that are placed on a fixture 310 that wraps around the examined subject 200 (Figure 1) but remains stationary with respect to the scanner (see Figure 4). Alternatively, the array of receive coils 353 do not remain stationary and are moved concurrently with the table motion. In either embodiment, during moving table imaging, the coils in the array receive in parallel. A moving table imaging reconstruction algorithm that integrates the parallel imaging reconstruction concept is used to reconstruct full-FOV images. It is to be appreciated that other rf coil array configuration, as are well-known in the art, may be employed with methods of the present invention. Other such configurations may include arranging coil array elements 300 of receive coil array 353 such that they wrap around only the anterior portion of subject 200, and/or additionally distribute along the frequency encoding direction.

**[0038]** Unlike a body coil, the B1 field of any of the receive coil array elements may vary spatially and induce image artifacts. Addressing the artifacts will be de-

scribed in greater detail below. The methods of imaging (acquisition and reconstruction) as described earlier with a moving table are applicable when employing a receive coil array rather than a body coil.

**[0039]** In embodiments employing receive coil arrays, data acquisition is conducted concurrently with table translation. The receivers' center frequencies are adjusted, or alternatively swept, at a rate commensurate with the table motion, which allows the scanner to follow a selected set of spins during each round of phase encodes. This enables each of the receivers, or alternatively channels, to acquire a coherent k-space data matrix and produce a regional image that maps out the set with negligible effects of the concurrent translation. Reduction of k-space sampling density is in effect in the present case, and leads to aliasing along the phase encoding direction(s) in each of the regional images. Applying SENSE or other parallel imaging reconstruction on the regional images that are produced in parallel generates a regional image free of aliasing. The process is repeated to produce a series of regional images of the volume of interest along the translation direction, which can be combined into a full-FOV image. In the presence of B1 field inhomogeneity however, the followed set of spins is "seen" by each coil with a different sensitivity weighting at different table locations, especially for embodiments that employ a stationary coil array 153 to receive signals during table translation. This leads to undesirable view-to-view changes that may cause significant ghosting artifacts. Two strategies may be applied to alleviate/eliminate this problem. First, one may design the coil array elements 300 to assume shapes that extend the full travel range of the selected spins, which is determined by the bandwidth of the signal filtration during each view acquisition, table translation speed, and pulse sequence timing. This reduces B1 field variation along the translation direction and hence lessens view-to-view changes. Second, one may, in the reconstruction, take into account both the B1 field maps and the table locations and correct for the view-to-view changes algebraically.

**[0040]** Embodiments of the present invention provide for a MRI system that may be employed as a whole body screening tool for metastatic cancer and other diseases. In the embodiments for the methods of extended volume imaging, various two-dimensional or three-dimensional MR pulse sequences (e.g. spin echo, fast spin echo, echo-planar, gradient echo, and FIESTA or FISP) may be employed. The imaging sequence may be one of multi-slice, multi-slab, and volume imaging sequences. Use of many MR pulse sequence is possible since only the phase or the frequency of the receiver and/or transmitter is modified during a scan. Embodiments of the methods of the present invention allow the user to select the desired direction of the phase and frequency encoding directions in order to advantageously place phase-encoding artifacts in desired directions. The user is also able to select interleaved acquisition of multiple slices,

if necessary.

**[0041]** In further embodiments, embodiments of the present invention are implemented as a hardware sub-system in the scanner that is independent of the pulse sequence itself. That way any pre-existing imaging strategy and information content can be obtained over the entire subject. A hardware system implementation would comprise incorporating a subsystem in the scanner that varies the receiver offset frequency or phase in response to changes in table position, or alternatively, changes the table position in response to changes in receiver frequency/phase.

**[0042]** For completeness, various aspects of the invention are set out in the following numbered clauses:

1. An imaging apparatus for producing Magnetic Resonance (MR) images of a subject (200), the apparatus comprising:

a magnet assembly (141) for producing a static magnetic field;

a gradient coil assembly (139) for generating a magnetic field gradient for use in producing MR images;

at least one radiofrequency (rf) coil array (353) disposed about the subject for transmitting a radiofrequency pulse and for detecting a plurality of magnetic resonance (MR) signals induced from the subject for a given imaging sequence;

a positioning device (134) for supporting the subject and for translating the subject during imaging; and,  
a plurality of receivers (250-252) for receiving the plurality of MR signals, the receivers each being adapted to adjust their respective center frequencies at a rate commensurate with a rate of translation of the positioning device.

2. The apparatus of clause 1 wherein the at least one rf coil array (353) is mounted on a fixture (310) that is disposed about the subject.

3. The apparatus of clause 2 wherein the fixture (310) and rf coil array (353) mounted thereon are stationary relative to the static magnetic field.

4. The apparatus of clause 2 wherein the fixture (310) and rf coil array (353) mounted thereon are moveable relative to the static magnetic field.

5. The apparatus of clause 1 wherein the at least one rf coil array (353) comprises a plurality of coil elements (300) arranged in a orthogonal distribution relative to a frequency encoding direction.

6. The apparatus of clause 1 wherein the at least one rf coil array (353) detects the MR signals concurrently with the translation of the positioning de-

vice (134).

7. The apparatus of clause 1 further comprising:

an image processor (106) for computing a plurality of respective sub-images corresponding to a field-of-view at a plurality of incremented locations of the subject and wherein the image processor is further adapted to combine the plurality of respective sub-images to form a composite image of the subject.

8. The apparatus of clause 1 wherein the imaging sequence is one of multi-slice, multi-slab, and volume imaging sequences.

9. A method for producing an image from an extended volume of interest within a subject (200) using a Magnetic Resonance Imaging (MRI) system where the extended volume of interest is larger than an imaging portion (142) of a magnet within the MRI system, the method comprising:

translating the volume using a positioning device (134) along an axis of the MRI system and imaging portions of the volume when they are within the imaging portion (142) of the magnet; detecting a plurality of MR signals from at least one radiofrequency (RF) coil array (353) for a given field-of-view within the MRI system as the positioning device is translating the volume; sending the plurality of MR signals to a plurality of receivers (250-252), the receivers each being adapted to adjust their respective center frequencies at a rate commensurate with a rate of translation of the positioning device, computing a plurality of respective sub-images corresponding to the plurality MR signals for each of the plurality of receivers and for the given field-of-view (FOV) at a plurality of incremented locations of the subject; and, combining the plurality of respective sub-images to form a composite image of the volume of interest.

10. The method of clause 9 wherein the at least one rf coil array (353) is mounted on a fixture (310) that is disposed about the subject.

11. The method of clause 10 wherein the fixture (310) and rf coil array (353) mounted thereon are stationary relative to the static magnetic field.

12. The method of clause 10 wherein the fixture (310) and rf coil array (353) mounted thereon are moveable relative to the static magnetic field.

13. The method of clause 9 wherein the at least one

rf coil array (353) comprises a plurality of coil elements (300) arranged in a orthogonal distribution relative to a frequency encoding direction.

14. The method of clause 9 wherein the detecting step is performed concurrently with the translating step.

15. The method of clause 9 wherein the translating step is repeated until a selected length of the subject has been imaged inside the imaging portion of the magnet.

16. The method of clause 9 wherein the combining step further comprises combining a central portion of each sub-image to form the composite image.

17. The method of clause 9 wherein the extended volume of interest is a head-to-toe view of the subject.

18. A method for imaging an extended volume of interest within a subject (200) using a Magnetic Resonance Imaging (MRI) system comprising:

translating the subject into an imaging portion (142) of a magnet assembly of the MRI system; detecting a plurality of MR signals from a radiofrequency (RF) coil array (353); and, sending the plurality of MR signals to a plurality of receivers, the receivers (250-252) each being adapted to adjust their respective center frequencies at a rate commensurate with a rate of translation of the positioning device; and, reconstructing at least one image of the volume of interest by computing a plurality of respective sub-images corresponding to the plurality MR signals for each of the plurality of receivers and for the given field-of-view (FOV) at a plurality of incremented locations of the subject as the subject is translated and combining the plurality of respective sub-images to form a composite image of the volume of interest.

19. The method of clause 18 wherein the extended volume of interest is a head-to-toe view of the subject.

20. The method of clause 18 wherein the at least one rf coil array (353) comprises a plurality of coil elements (300) arranged in orthogonal distribution to a frequency encoding direction.

21. The method of clause 18 wherein the at least one fg coil array (353) is mounted on a fixture (310) that is disposed about the subject (200).

22. The method of clause 21 wherein the fixture and

rf coil array mounted thereon are stationary relative to the static magnetic field.

23. The method of clause 21 wherein the fixture and rf coil array mounted thereon are moveable relative to the static magnetic field.

24. The method of clause 18 wherein the detecting step is performed concurrently with the translating step.

25. The method of clause 18 wherein the translating step is repeated until a selected length of the subject has been imaged.

26. The method of clause 18 wherein the translating step is substantially continuous.

## Claims

1. An imaging apparatus for producing Magnetic Resonance (MR) images of a subject (200), the apparatus comprising:

a magnet assembly (141) for producing a static magnetic field;  
a gradient coil assembly (139) for generating a magnetic field gradient for use in producing MR images;  
at least one radiofrequency (rf) coil array (353) disposed about the subject for transmitting a radiofrequency pulse and for detecting a plurality of magnetic resonance (MR) signals induced from the subject for a given imaging sequence;  
a positioning device (134) for supporting the subject and for translating the subject during imaging; and,  
a plurality of receivers (250-252) for receiving the plurality of MR signals, the receivers each being adapted to adjust their respective center frequencies at a rate commensurate with a rate of translation of the positioning device.

2. The apparatus of claim 1 wherein the at least one rf coil array (353) comprises a plurality of coil elements (300) arranged in a orthogonal distribution relative to a frequency encoding direction.

3. The apparatus of claim 1 wherein the at least one rf coil array (353) detects the MR signals concurrently with the translation of the positioning device (134).

4. The apparatus of claim 1 further comprising:

an image processor (106) for computing a plurality of respective sub-images corresponding



- to a field-of-view at a plurality of incremented locations of the subject and wherein the image processor is further adapted to combine the plurality of respective sub-images to form a composite image of the subject.
5. A method for producing an image from an extended volume of interest within a subject (200) using a Magnetic Resonance Imaging (MRI) system where the extended volume of interest is larger than an imaging portion (142) of a magnet within the MRI system, the method comprising:
- translating the volume using a positioning device (134) along an axis of the MRI system and imaging portions of the volume when they are within the imaging portion (142) of the magnet; detecting a plurality of MR signals from at least one radiofrequency (RF) coil array (353) for a given field-of-view within the MRI system as the positioning device is translating the volume; sending the plurality of MR signals to a plurality of receivers (250-252), the receivers each being adapted to adjust their respective center frequencies at a rate commensurate with a rate of translation of the positioning device, computing a plurality of respective sub-images corresponding to the plurality of MR signals for each of the plurality of receivers and for the given field-of-view (FOV) at a plurality of incremented locations of the subject; and, combining the plurality of respective sub-images to form a composite image of the volume of interest.
6. A method for imaging an extended volume of interest within a subject (200) using a Magnetic Resonance Imaging (MRI) system comprising:
- translating the subject into an imaging portion (142) of a magnet assembly of the MRI system; detecting a plurality of MR signals from a radiofrequency (RF) coil array (353); and, sending the plurality of MR signals to a plurality of receivers, the receivers (250-252) each being adapted to adjust their respective center frequencies at a rate commensurate with a rate of translation of the positioning device; and, reconstructing at least one image of the volume of interest by computing a plurality of respective sub-images corresponding to the plurality MR signals for each of the plurality of receivers and for the given field-of-view (FOV) at a plurality of incremented locations of the subject as the subject is translated and combining the plurality of respective sub-images to form a composite image of the volume of interest.
7. The method of claim 5 or claim 6 wherein the detecting step is performed concurrently with the translating step.
8. The method of claim 5 or claim 6 wherein the translating step is repeated until a selected length of the subject has been imaged inside the imaging portion of the magnet.
9. The method of claim 5 or claim 6 wherein the combining step further comprises combining a central portion of each sub-image to form the composite image.
10. The method of claim 5 or claim 6 wherein the translating step is substantially continuous.

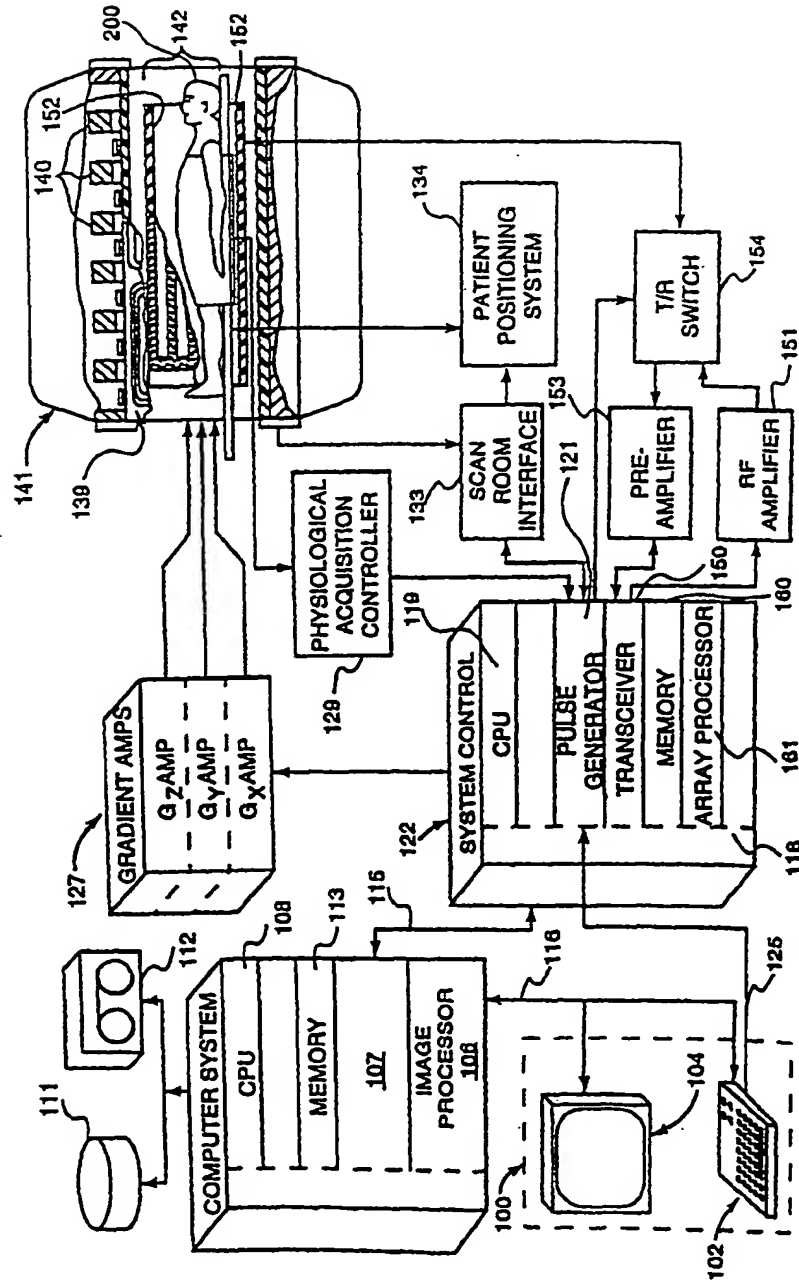


FIG.1

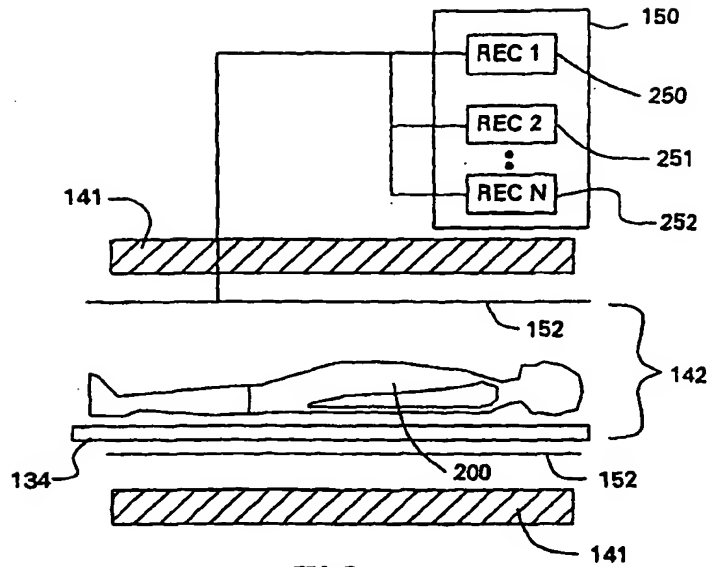


FIG. 2

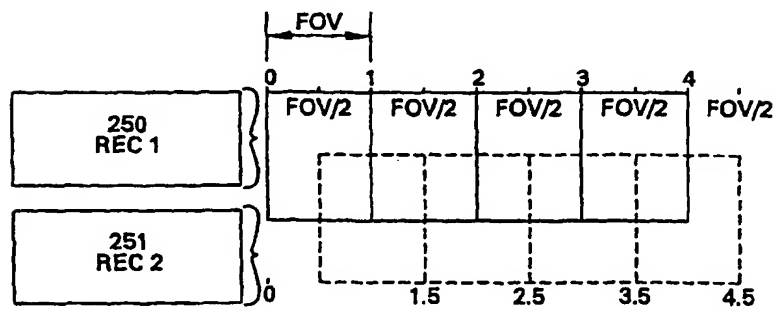


FIG. 3

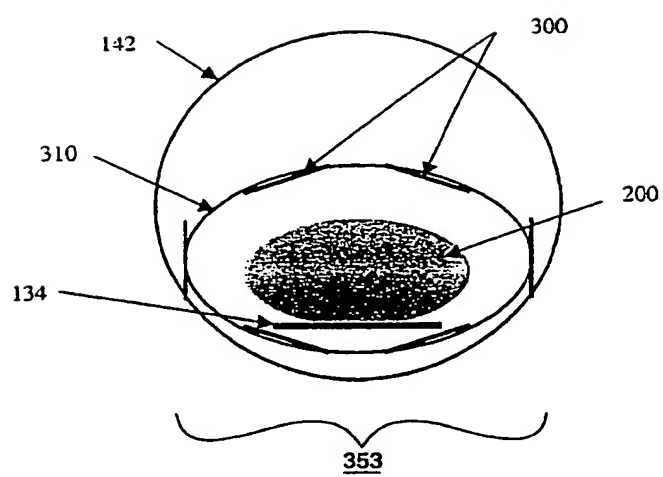


FIG.4